### WINSTAR Display

# **OLED SPECIFICATION**

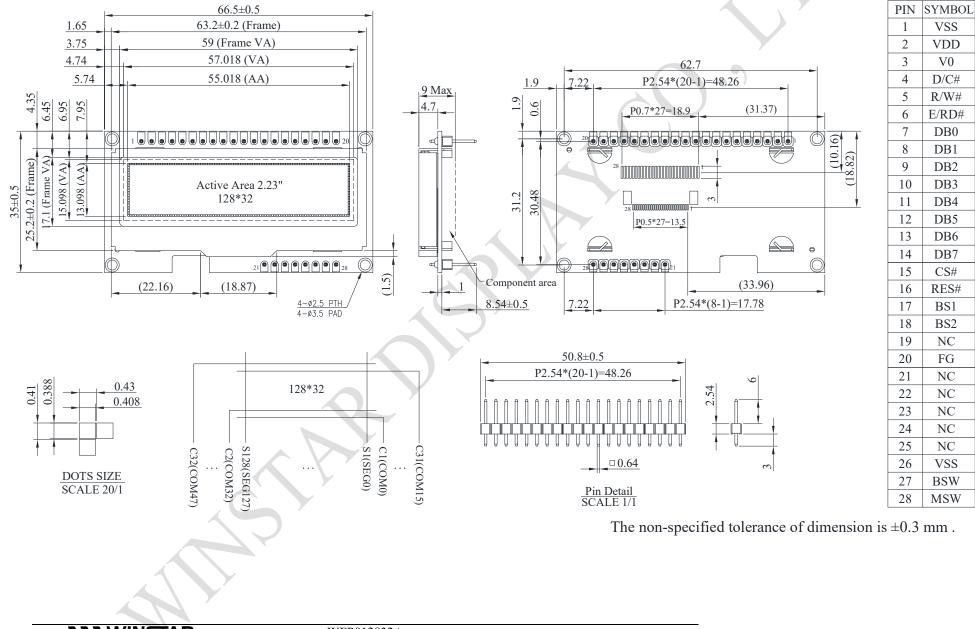
Model No:

WEP012832A

## **General Specificatio**

ltem	Dimension	Unit			
Dot Matrix	128 x 32 Dots	-			
Module dimension	66.5 x 35.0 x 9.0(Max)	mm			
Active Area	55.018 x 13.098	mm			
Pixel Size	0.408 x 0.388	mm			
Pixel Pitch	0.43 x 0.41	mm			
Display Mode	Passive Matrix				
Display Color	Monochrome				
Drive Duty	1/32 Duty				
IC	SSD1305				
Buzzer	OBO-11241SB				
Vibration Motor	W0625AB001F				
Interface	6800,8080,SPI,I2C				
Size	2.23 inch				

#### **Contour Drawing & Block Diagram**



**WINSTAR** 

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### **Interface Pin Function**

No.	Symbol	Function
1	VSS	Ground.
2	VDD	Power supply pin for core logic operation.
3	V0	Power supply for panel driving voltage. No connection.
4	D/C#	This is Data/Command control pin. When it is pulled HIGH (i.e. connect to VDDIO), the data at D[7:0] is treated as data. When it is pulled LOW, the data at D[7:0] will be transferred to the command register. In I2C mode, this pin acts as SA0 for slave address selection.
5	R/W#	This is read / write control input pin connecting to the MCU interface. When interfacing to a 6800-series microprocessor, this pin will be used as Read/Write (R/W#) selection input. Read mode will be carried out when this pin is pulled HIGH (i.e. connect to VDDIO) and write mode when LOW. When 8080 interface mode is selected, this pin will be the Write (WR#) input. Data write operation is initiated when this pin is pulled LOW and the chip is selected. When serial interface is selected, this pin must be connected to VSS.
6	E/RD#	When interfacing to a 6800-series microprocessor, this pin will be used as the Enable (E) signal. Read/write operation is initiated when this pin is pulled HIGH (i.e. connect to VDDIO) and the chip is selected. When connecting to an 8080-microprocessor, this pin receives the Read (RD#) signal. Read operation is initiated when this pin is pulled LOW and the chip is selected. When serial interface is selected, this pin must be connected to VSS.
7~14	DB0~DB7	These are 8-bit bi-directional data bus to be connected to the microprocessor's data bus. When serial interface mode is selected, D0 will be the serial clock input: SCLK; D1 will be the serial data input: SDIN and D2 should be left opened. When I2C mode is selected, D2, D1 should be tied together and serve as SDAout, SDAin in application and D0 is the serial clock input, SCL.
15	CS#	This pin is the chip select input. (active LOW)
16	RES#	This pin is reset signal input. When the pin is LOW, initialization of the chip is executed. Keep this pin HIGH (i.e. connect to VDDIO) during normal operation.

		Communicating Protocol Select. These pins are MCU interface selection input. See the following table:						
17,18	BS2,BS1		68XX-parallel	80XX-parallel	Serial	I2C		
		BS1	0	1	0	1		
		BS2	1	1	0	0		
19	N.C.	No conne	No connection.					
20	FG(GND)	Ground.	Ground.					
21~25	N.C.	No conne	No connection.					
26	VSS	Ground.						
27	BSW	PWM for the Piezoelectric Buzzer.						
28	MSW	Control the BLDC Vibration Motor.						

### **Absolute Maximum Ratings**

Parameter	Symbol	Min	Max	Unit
Supply Voltage for Logic	VDD	-0.3	4.0	V
Operating Temperature	TOP	-40	+80	°C
Storage Temperature	TSTG	-40	+85	°C

#### **Electrical Characteristics**

#### **DC Electrical Characteristics**

ltem	Symbol	Condition	Min	Тур	Мах	Unit
Supply Voltage for Logic	VDD	- 1	3.0	3.3	3.5	V
Input High Volt.	VIH		0.8×VDD	_	VDD	V
Input Low Volt.	VIL	X-Y	0	_	0.2×VDD	V
Output High Volt.	VOH	IOUT = 100uA, 3.3MHz	0.9×VDD		VDD	V
Output Low Volt.	VOL	IOUT = 100uA, 3.3MHz	0		0.1×VDD	V
Supply Voltage for Buzzer	BSW	50% square	0.8×VDD	_	VDD	V
Supply Voltage for Vibration Motor	MSW	_	2.7	_	3.3	V
Operating Current at Display with 50% Check Board	IDD	VDD=3.3V	-	90	120	mA